

ETConcept

Systems Engineering

Wiegand to RS232 Converter

W2RS232

User's Guide



CE

V1.4
2009

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List of Accessories Included

The packaged include the following items:

Wiegand to RS232 Converter (W2RS232)



User's Guide

2x- CTF female connectors

List of Required Accessories (not included)

To install the convert the following item are required:

ScrewDrivers



Power Supply



Null-Modem Cable





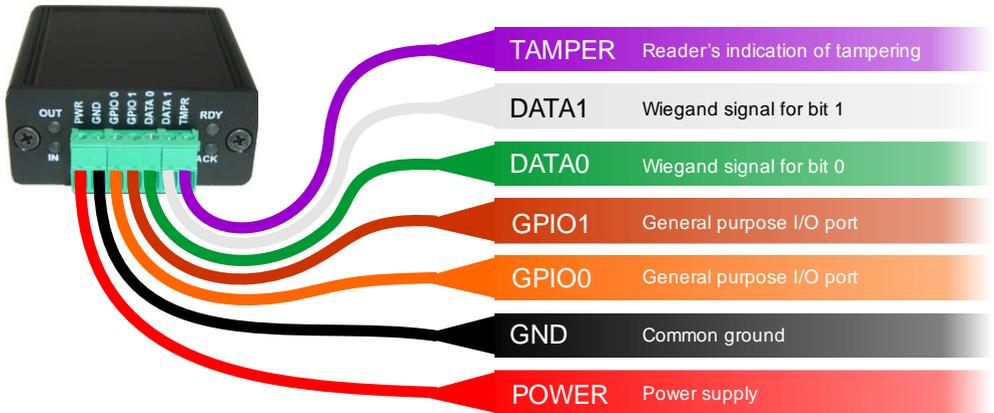
Quick Installation

To install the converter follow the steps below:

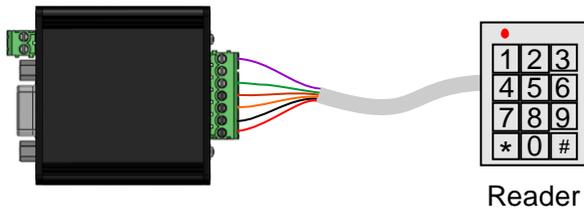
1. Verify the package contents (see the list of accessories included)



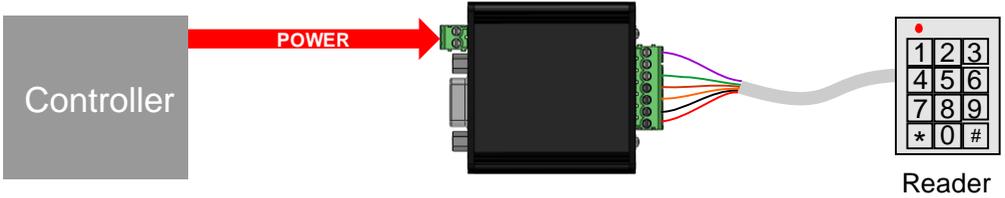
2. Connect the reader/controller Wiegand interface to the CTF terminal block
 - a. Follow the connection diagram below and use the screwdriver



b. Plug the CTF terminal block to the converter



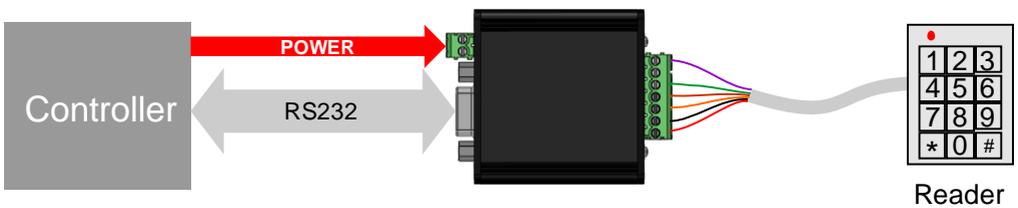
3. Connect the converter to the power supply



4. Confirm that the correct mode has been detected (Input or Output):

a) If the converter isn't in the correct mode repeat step 3.

5. Then connect the serial cable to the controller.





General Information

Wiegand converters were developed for the security market to connect control access equipments like, for example, keypads and card readers with Wiegand interface, to other interfaced equipments like for example the serial port of a computer. This family of bidirectional Wiegand converters can convert data in binary format to Wiegand and vice-versa. The converter's setup is reduced to minimum for rapid installation.

The Converter has two working modes: input-mode and output-mode, explained in detail on the next subchapters.

Operating in Input Mode

The converter will operate in **Input-Mode** when connected to the **output interface** of a Wiegand compliant device e.g., a keypad or card-reader. In this mode, the converter will automatically convert a Wiegand 6-bit up to 96-bit input sequence to a formatted binary frame, see command set. It will



also detects changes on the Tamper input signal and reports to the controller. The converter sets the two general purpose I/O to output and will accept commands from the serial interface to control the GPIO₀ and GPIO₁. Figure 1 shows a conceptual diagram of the Wiegand converter in input mode and the data flow directions.

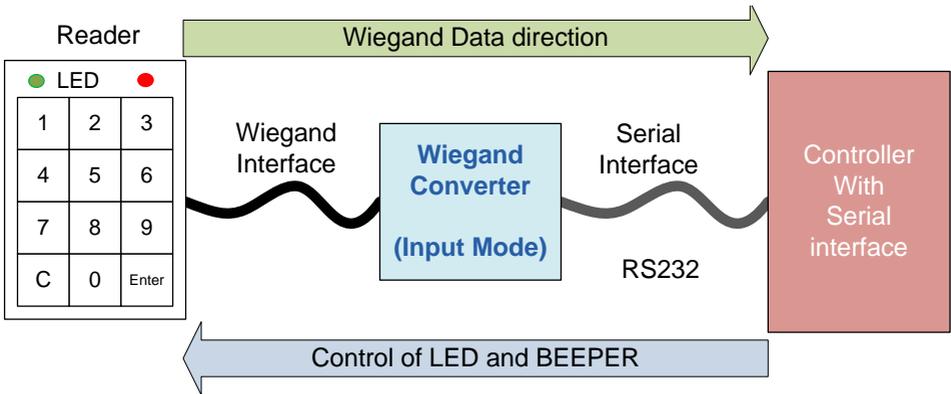


Figure 1 Conceptual diagram of the Wiegand converter dataflow on input mode



Wiegand interface Panel LED Signaling for Input-Mode

Waiting Wiegand frame in Input-Mode

The converter is connected to the Wiegand interfaced equipment waiting for Wiegand frames from Wiegand Interface and commands from the RS232 interface.



Processing data in Input-Mode

The converter is processing the received Wiegand frame or command. After processing the converter returns to the **Waiting Wiegand frame** state.





Operating in Output Mode

The converter will operate in **Output-Mode** in two situations: when connected to the **input interface** of a Wiegand compliant device or if not connected to any device. In this mode, the converter will convert data received from the serial interface to Wiegand frames. It will also accept commands to control the Tamper signal. Changes in the general purpose inputs GPIO are converted to commands and sent out through the serial interface. Figure 2 shows a conceptual diagram of the wiegand converter in input mode and the data flow directions.

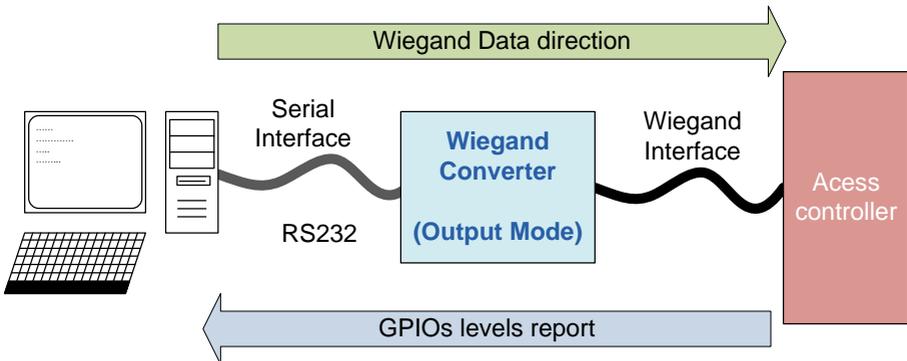


Figure 2 Conceptual diagram of the Wiegand converter dataflow on output mode



Wiegand interface Panel LED Signaling for Output-mode

Waiting command in Output-Mode

The converter is waiting for commands from the RS232 interface and changes on the GPIOs or Tamper ports



Processing data in Output-Mode

The converter is processing the received command. After the processing and sending the wiegand frame the converter return to **Waiting command** state.





Command Set

The Wiegand converter is bidirectional and converts Wiegand frames on both directions. These frames follow the following basic structure:

Byte					Byte		
N-1	N-2	N-3	N-4	...	2	1	0
Sync		ID	Command Data			-	CR

Byte N-1	Sync : Frame synchronization pattern. Value = 55 _h 55 _h
Byte N-2	ID : Command Identification. Values 00 _h – Reserved 01 _h – Wiegand frame Command 02 _h – Tamper Signal 03 _h – GPIO ₀ Signal 04 _h – GPIO ₁ Signal 05 _h to 08 _h – Reserved 09 _h – Write to EEPROM 0A _h – Force Reset 0B _h – Dump EEPROM data to terminal 0C _h to FF _h – Reserved
Byte N-3	
Byte N-4 a	
Byte 2	Command Data : Command Specific Data. (See commands)
Byte 1	Reserved for future use
Byte 0	CR : <i>Carriage Return character</i> Value = 0D _h



The transmission order on the serial channel is the most-significant byte first (N-1). The two most-significant bytes are the synchronization pattern field frame detection. The next byte is the identification field that stores the command identity, followed by the command's data. All commands finish with a carriage return character.

Wiegand Frame

When the converter is operating in Input-Mode and receives Wiegand frame, it issues a command on the serial interface. When operating in Output-Mode, the same command received on the serial interface will generate the corresponding Wiegand frame. The Wiegand frame command is presented in the following structure:

Byte															Byte				
19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Sync		ID	N _B	WDATA											T _P	T _B	CR		



Byte 19-18	Sync : Frame synchronization pattern. Value $55_h 55_h$
Byte 17	ID : Command Identification. Value 01_h
Byte 16	N_B : Wiegand frame size (including parity bits). Value from 6 to 96
Byte 15-4	WDATA : Wiegand Data including parity bits.
Byte 3	TP : Wiegand Pulse width (Not implemented on this version)
Byte 2	TB : Wiegand Bit Period (Not implemented on this version)
Byte 1	Reserved for future use
Byte 0	CR : Caracter terminador (<i>Carriage Return character</i>) Valor = $0D_h$

The TP and TB fields represent the timing specifications of the Wiegand pulse width, t_p , and the bit period, t_B , as shown in Figure 3.

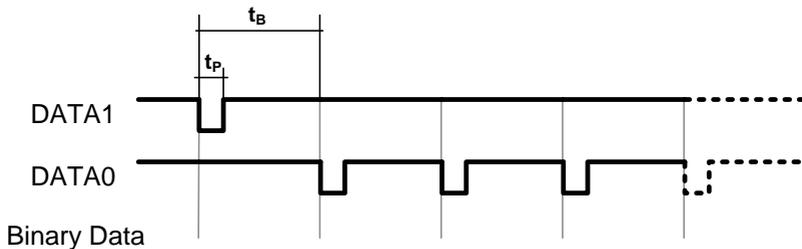


Figure 3 - Wiegand data timings.



Figure 4 presents a conversion example of a 26bit Wiegand frame with a pulse width of 100µs and a bit period of 1ms. Both signals for DATA1 and DATA0 of the Wiegand interface are shown, with the corresponding converted frame.

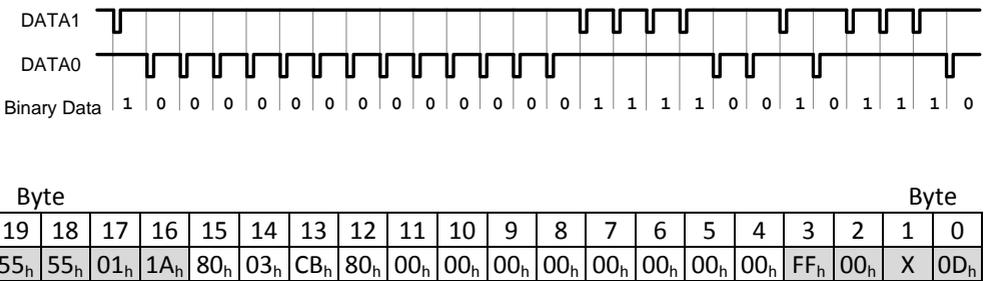


Figure 4 - 26bit Wiegand Frame conversion example.

The converter needs a standby period t_w between Wiegand frames in order to process and transmit data, as shown in Figure 5. For example, a 26 bit Wiegand frame with a 1ms bit period must have minimum standby period of 26ms.

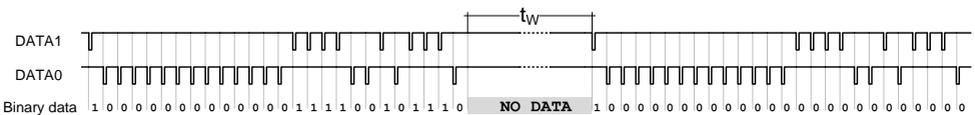


Figure 5 - Standby period between Wiegand frames



TAMPER Signal

When operating in Input-Mode, the converter will issue a TAMPER signal command every time the tamper signal changes state. If operating in Output-Mode, a TAMPER signal command will cause an update to this output signal, with the appropriate received value. The command has the following structure:

Byte		Byte			
5	4	3	2	1	0
Sync		ID	B _T	-	CR

Byte N-1	<p>Sync : Frame synchronization pattern. Value = 55_h 55_h</p> <p>ID : Command Identification. Value 02_h</p> <p>B_T: Tamper Signal Value Value 00_h Tamper Signal is 0 FF_h Tamper Signal is 1</p> <p>Reserved for future use</p> <p>CR: <i>Carriage Return character</i> Value = 0D_h</p>
Byte N-2	
Byte N-3	
Byte 2	
Byte 1	
Byte 0	



GPIO₀ Signal

When operating in Input-Mode, the converter will update the GPIO₀ signal with a value received in a GPIO₀ signal command. If operating in Output-Mode, a GPIO₀ signal command is issued every time the GPIO₀ signal changes state. The command has the following structure:

Byte		Byte			
5	4	3	2	1	0
Sync		ID	B ₀	-	CR

Byte N-1

Byte N-2

Byte N-3

Byte 2

Byte 1

Byte 0

Sync : Frame synchronization pattern. Value = 55 _h 55 _h
ID : Command Identification. Value 03 _h
B₀ : Tamper Signal Value Value 00 _h GPIO ₀ Signal is 0 FF _h GPIO ₀ Signal is 1
Reserved for future use
CR : Carriage Return character Value = 0D _h



GPIO₁ Signal

When operating in Input-Mode, the converter will update the GPIO₁ signal with a value received in a GPIO₁ signal command. If operating in Output-Mode, a GPIO₁ signal command is issued every time the GPIO1 signal changes state. The command has the following structure:

Byte		Byte			
5	4	3	2	1	0
Sync		ID	B ₁	-	CR

Byte N-1

Byte N-2

Byte N-3

Byte 2

Byte 1

Byte 0

Sync : Frame synchronization pattern. Value = 55 _h 55 _h
ID : Command Identification. Value 04 _h
B₁ : Tamper Signal Value Value 00 _h GPIO1 Signal is 0 FF _h GPIO1 Signal is 1
Reserved for future use
CR : <i>Carriage Return character</i> Value = 0D _h



Write to EEPROM

This command writes a byte on the converter's EEPROM memory. The EEPROM memory addresses affected by the command are the configurations zone (the first 6 bytes). The new configurations only take effect on the next reset. The command has the following structure:

Byte			Byte			
6	5	4	3	2	1	0
Sync		ID	Address	Data	-	CR

Byte N-1

Byte N-2

Byte N-3

Byte 3

Byte 2

Byte 1

Byte 0

Sync : Frame synchronization pattern. Value = 55 _h 55 _h
ID : Command Identification. Value 09 _h
Address : Value between 00 _h and 0F _h
Data : Value between 00 _h and FF _h
Reserved for future use
CR : <i>Carriage Return character</i> Value = 0D _h



EEPROM Address Map

Address	Type	Value	Descriptions
00 _h	Byte	A5 _h	Working mode Auto (Default)
		0F _h	Input mode allways
		F0 _h	Output mode allways
01 _h 02 _h	Int	0D _h 00 _h	Defines the T _p time (50μs) (Default)
		1A _h 00 _h	Defines the T _p time (100μs)
03 _h 04 _h	Int	9A _h 15 _h	Defines the T _b time (2 ms) (Default)
		CD _h 0A _h	Defines the T _b time (1 ms)
05 _h 06 _h	Int	FF _h C9 _h	Defines the Time-Out (5 ms) (Default)
07 _h	Byte	01 _h	Defines Binary Format (Default)
		02 _h	Defines ASCII Format
08 _h	Byte	10 _h (Init value)	Next position for the Event Log
10 _h -FF _h		-	Event Log (Stores all events i.e Reset, PowerUp and several other events).

Soft Reset

This command forces a reset. Two seconds after the receptions of this command the converters restarts. The command has the following structure:



Byte				Byte	
5	4	3	2	1	0
Sync			ID	x	CR

Byte N-1	Sync : Frame synchronization pattern. Value = 55 _h 55 _h	
Byte N-2		
Byte N-3		ID : Command Identification. Value 0A _h
Byte 2		Don't care
Byte 1		Reserved for future use
Byte 0	CR : <i>Carriage Return character</i> Value = 0D _h	

EEPROM memory dump

This command dumps the EEPROM contents to the serial interface. The command has the following structure:



Byte				Byte	
5	4	3	2	1	0
Sync		ID	x	-	CR

Byte N-1	Sync : Frame synchronization pattern. Value = 55 _h 55 _h
Byte N-2	
Byte N-3	ID : Command Identification. Value 0B _h
Byte 2	Don't care
Byte 1	Reserved for future use
Byte 0	CR : <i>Carriage Return character</i> Value = 0D _h

ASCII Output Format

When the converter is set to ASCII output format all the data is converted to the equivalent, ASCII, Hexadecimal value until output. Except for sync pattern and the stop char (0D_h).

The example on the Wiegand Frame section will be outputted as follows:

UU011A8003CB800000000000000000FF0000<CR>



ATTENTION: When the converter is set to ASCII output all the commands must be send in ASCII format as well.

To set the converter to ASCII output format the followig command must be send:

55 _h	55 _h	09 _h	07 _h	02 _h	X	0D _h
-----------------	-----------------	-----------------	-----------------	-----------------	---	-----------------

To return to the Binary output the following command must be send:

UU09070100<CR>

CUSTOM COMMANDS

Custom commands can be provided to adjust the converter to specific project needs. Contact ETConcept for further information on this subject.



Product Specifications

Electrical Characteristics	
Operating Voltage Range	Min. 7V DC Max. 16V DC
Current Consumption	Typ. 30mA
Environmental Characteristics	
Operating Environment	Indoor and Outdoor ¹⁾
Operating Temperature Range ²⁾	0°C to 70°C
Operating Humidity	0 - 95% (non-condensing)
Storage	-40°C - 70°C and 0 - 95% (non-condensing)
Wiegand Interface	
Wiegand Format Length	From 6 bits to 96 bits
Idle Period	Min. 30ms
Wiegand Pulse Width	Min. 50µs and Max. 200µs
Wiegand Bit Period	1ms, 2ms
General Purpose I/O	2
Tamper Signal	1 Port to read/write the TAMPER signal



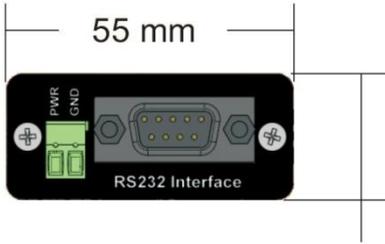
RS232 Interface	
Communication Distance	Up to 50m
Communication Modes	Full-Duplex without flow control
Baud Rate ³⁾	9600
Mechanical Characteristics	
Weight	75 g
Dimensions	55 mm x 72 mm x 24 mm ⁴⁾
Enclosure material	Anodized Aluminium

Notes:

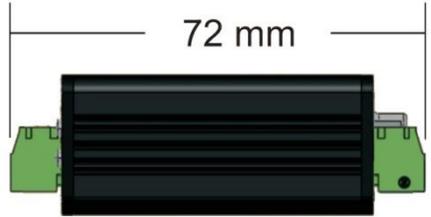
- 1) For Outdoor applications the converter must be protected against direct rain and direct sun exposure;
- 2) Other temperature ranges are available on demand;
- 3) Other Baud Rates are available on demand;
- 4) Dimensions include the terminal block CTF connectors.



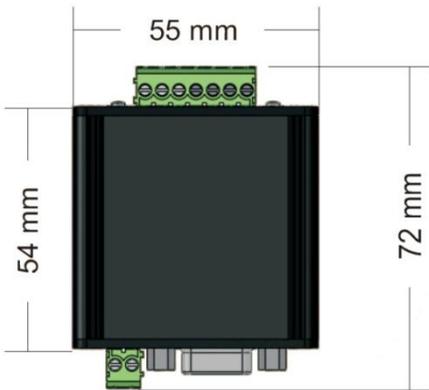
Mechanical Specifications



Front View



Side View



Top View

Note: All dimensions are in millimeters



CE Statement of Conformity

Manufacturer: ETConcept, Systems Engineering

Address: Bairro da Paradela
Rua Jacinto Duarte, Lt.97
2660-270 Santo António dos Cavaleiros
Portugal

Type of Equipment: Wiegand to RS232 Converter

Model: W2RS232

Council directives applied: 2004/108/CE

Year mark applied: 2008

The product has been tested in the typical installation configuration and with peripherals complying with the above listed Directives. I, the Undersigned, hereby declare that the above mentioned equipment conforms to the requirements of the Directives specified above, when installed in accordance with the manufacturer specifications.

01/07/2008

Mr. João Casaleiro



Product Manager



Important Information

This manual provides information on how to setup and interface the Wiegand to RS232 Converter (W2RS232). It has been written for experienced users to setup the system within the shortest time. Please take special care to all specifications and do not hesitate to contact ETConcept for any additional support.

Warranty

This ETConcept product is warranted against defects in material and workmanship for a period of two years from the date of shipment, as evidenced by receipts or other documentation. Duration and conditions of warranty for this product may be superseded when the product is integrated into (becomes a part of) other ETConcept products. During the warranty period, ETConcept will, at its option, either repair or replace products which prove to be defective.

The warranty period begins on the date of delivery or on the date of installation if installed by ETConcept.



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For warranty service or repair, this product must be returned to a service facility designated by ETConcept.

For products returned to ETConcept for warranty service, the Buyer shall prepay shipping charges to ETConcept and ETConcept shall pay shipping charges to return the product to the Buyer. However, the Buyer shall pay all shipping charges, duties, and taxes for products returned to ETConcept from another country.

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The installation of this product will not be covered by warranty if not executed by ETConcept. In addition, ETConcept does not



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